



JOINT EUROPEAN RESEARCH INFRASTRUCTURE NETWORK FOR COASTAL OBSERVATORIES

Land based remote sensing techniques

19th June 2017



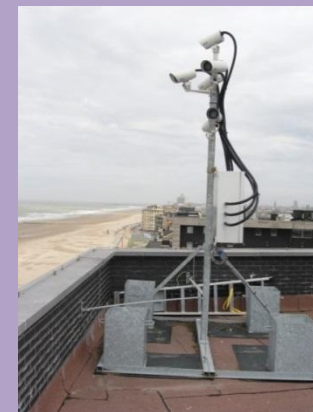
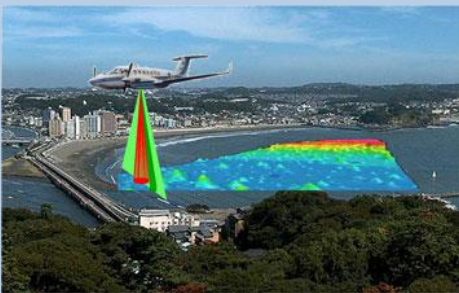
The coast: a variety of functions



- Safety against flooding
- Recreation
- Accommodate communities
- Nature conservation
- Ports



Monitoring Coastal Physics



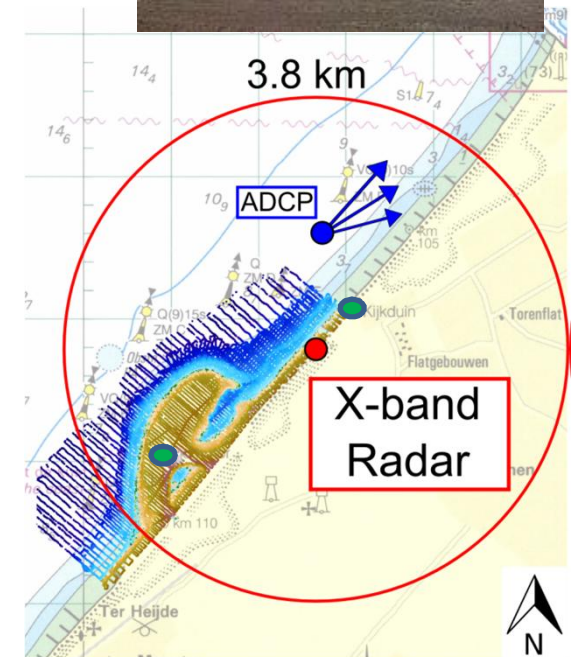
HF radar-X-band radar –Video

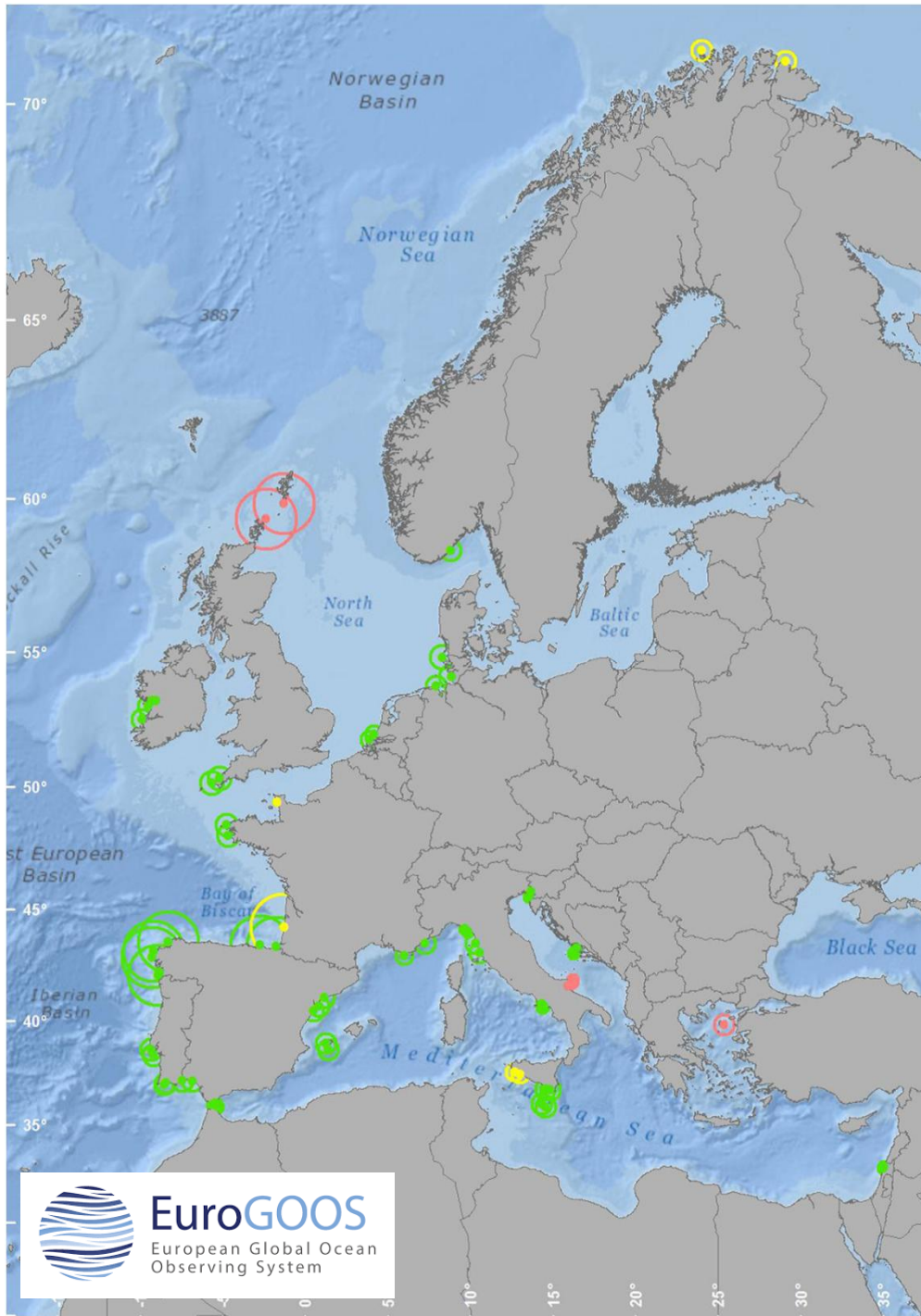


HF radar Wera



Argus video tower
12 cameras



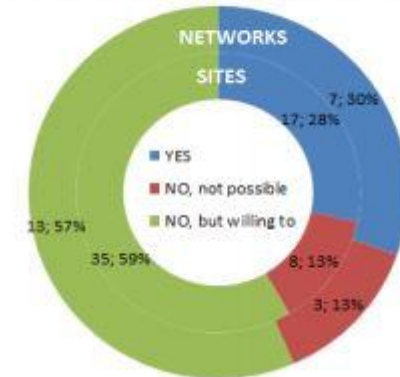


HF radar sites

Surface Currents (and waves)

52 Europe

Number of connected networks/sites

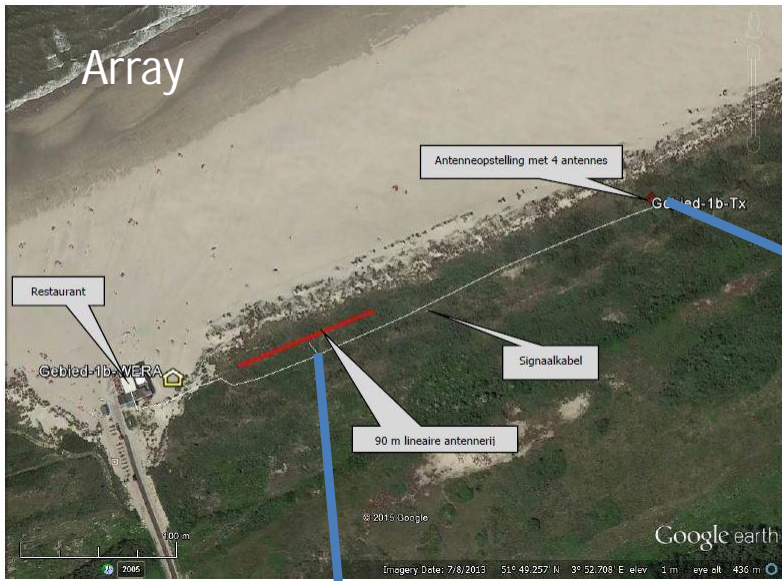


GREEN: ONGOING

RED: PAST

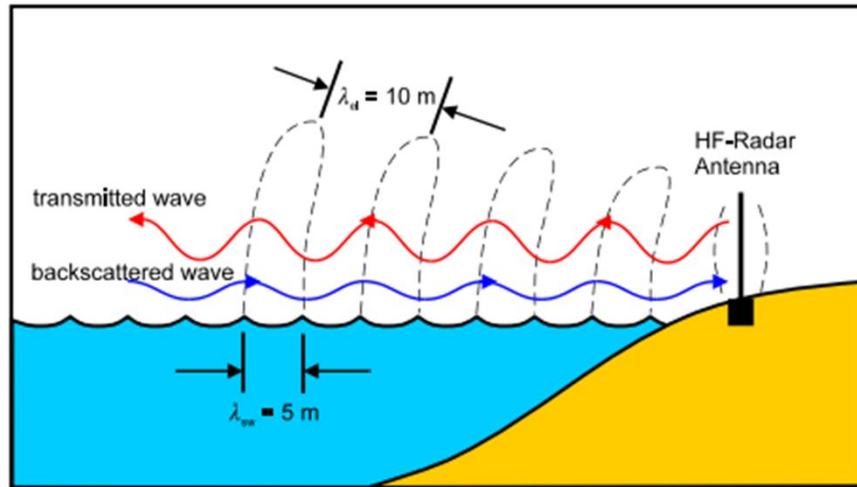
YELLOW: FUTURE





Bragg reflection

3 to 30 MHz



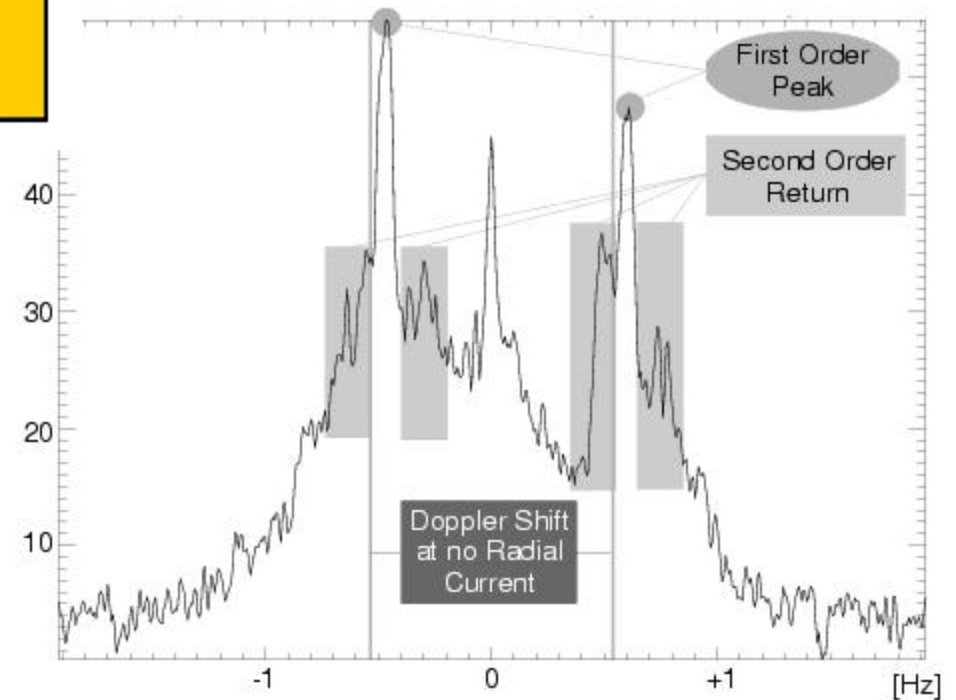
Reflection from waves at $\frac{1}{2}$ wavelength

Moving away from source and coming towards source

Result in opposite shifts

Additional shift in same direction due to currents

You can only detect the component coming towards or moving away from you





The port of Rotterdam

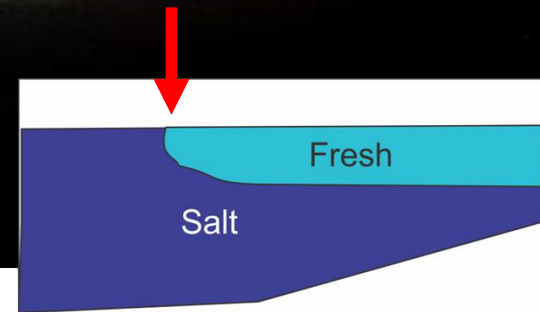


Hydrodynamics at outflow of river Rhine

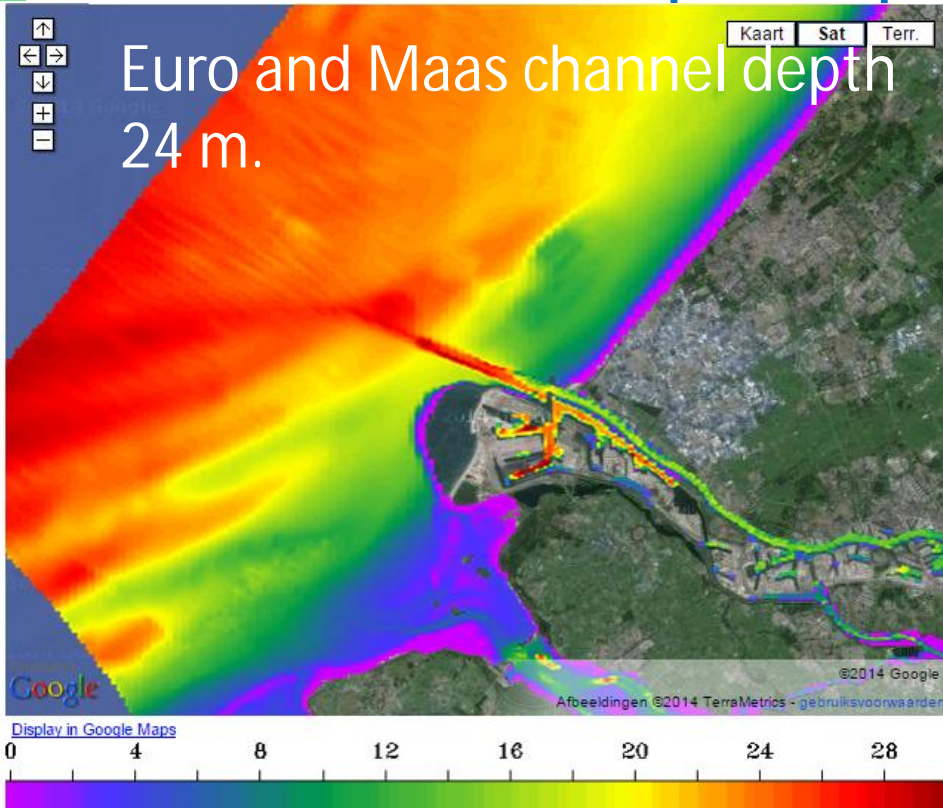




Hydrodynamics at outflow of river Rhine



Access to the port Rotterdam: JERICO^{next} pilots perspective



Tide

Swell

Cross currents

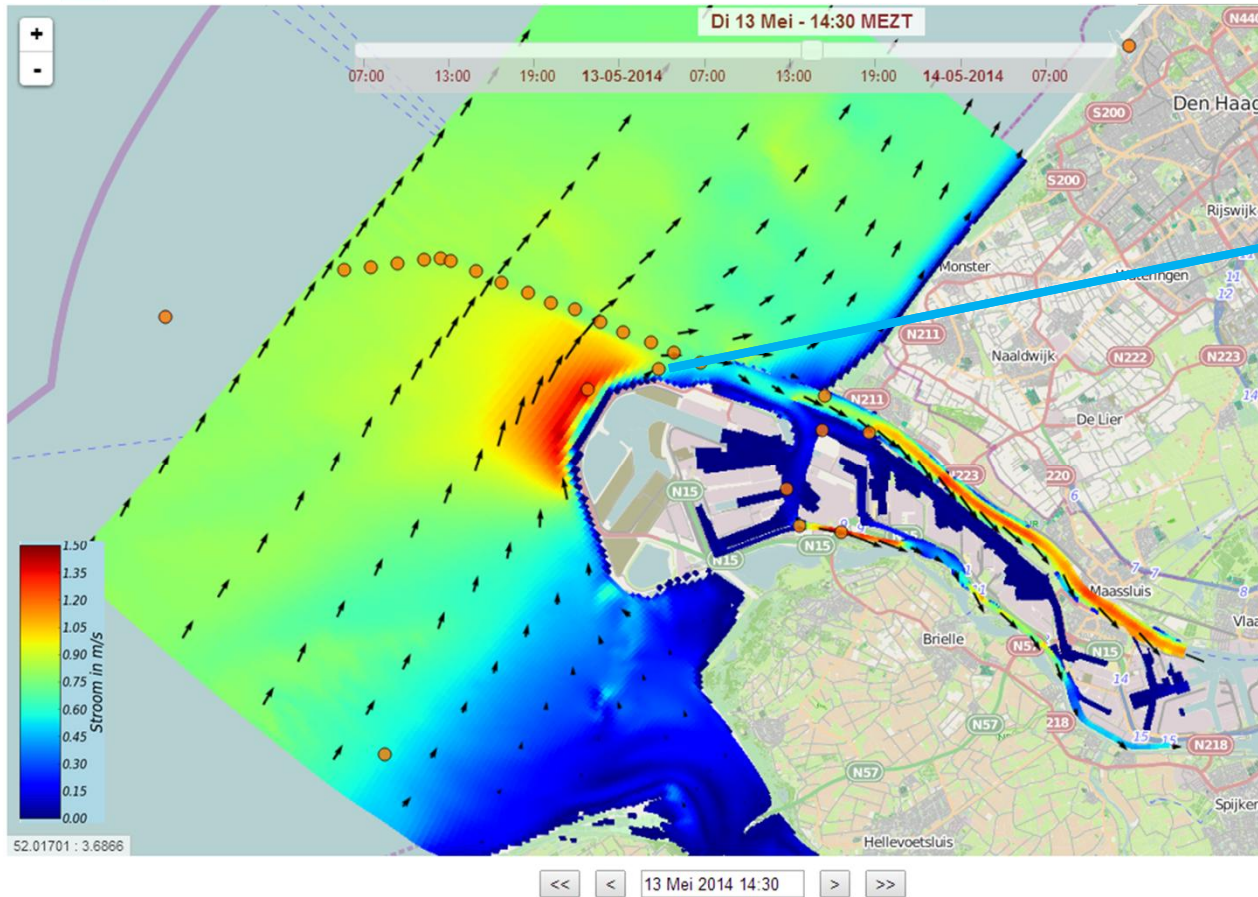
} time window



Rijkswaterstaat
Ministry of Infrastructure and the
Environment

Deltares
Enabling Delta Life

Previous set-up current information



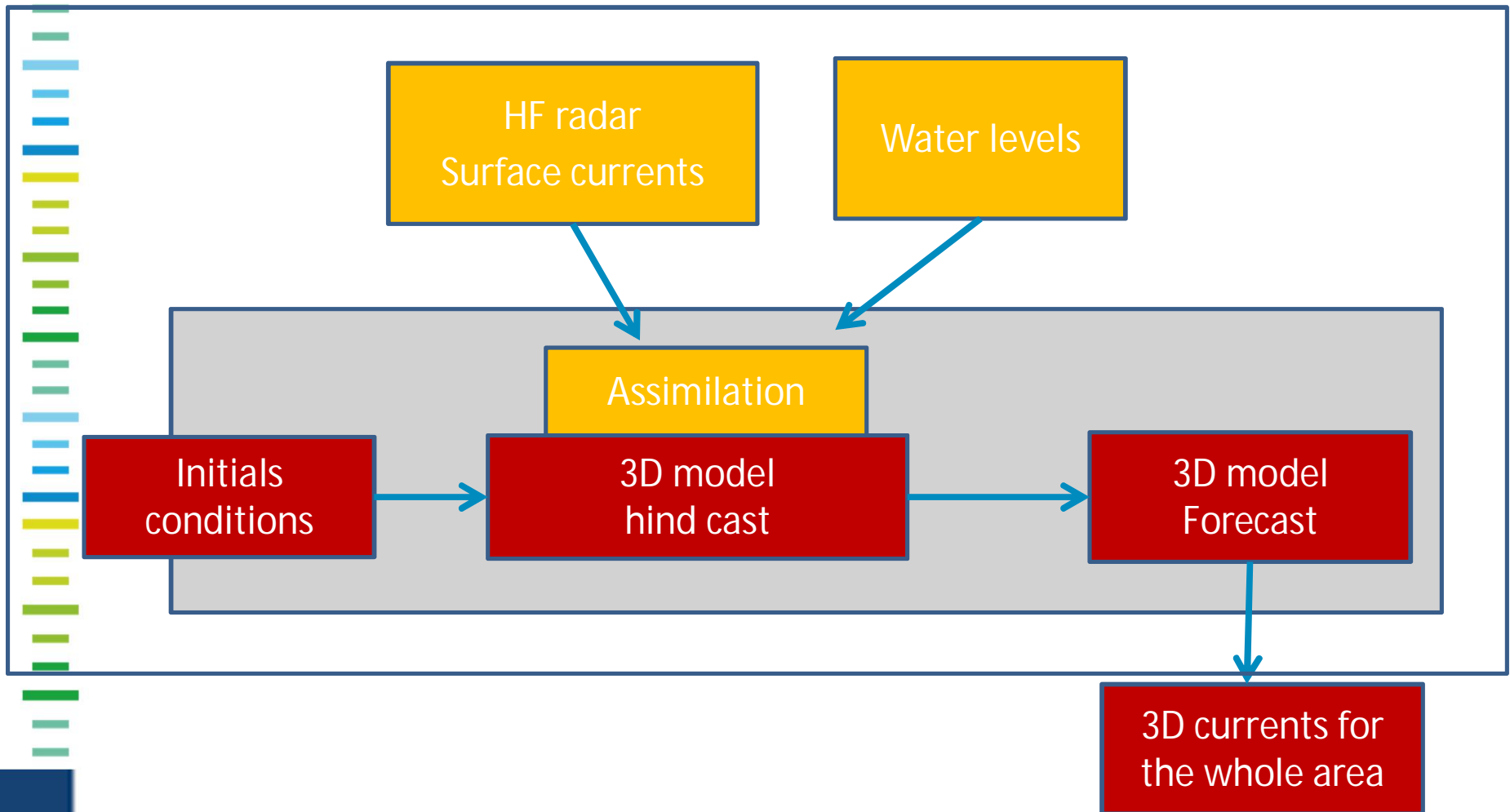
Pole with ADCP's



2D hydrodynamic forecast model → depth averaged currents

Proposal 2014

3D forecast & HF radar



Why HF radar?



- Spatial current measurements supply:
 - Better option to fit with spatial model (compared to points)
 - Captures features not fully resolved by hydrodynamic model
 - Low “down time” due to:
 - High stability/performance of the technique
 - Easy access to equipment in case of failures
 - Draw back:
 - Only surface current in highly 3D flow environment
- Challenges:
- Stability at high wave conditions
 - Resolving gradients
 - Shadowing effect of land reclamation
 - Anchored and moving ships/ cranes etc.



Functional specs HF radar



Area of interest

A: vectors

A+B: radials

Representative depth:

0.5 m

Spatial resolution

around 1.5 km

Maximum uncertainty

20 cm/s in 30 min.

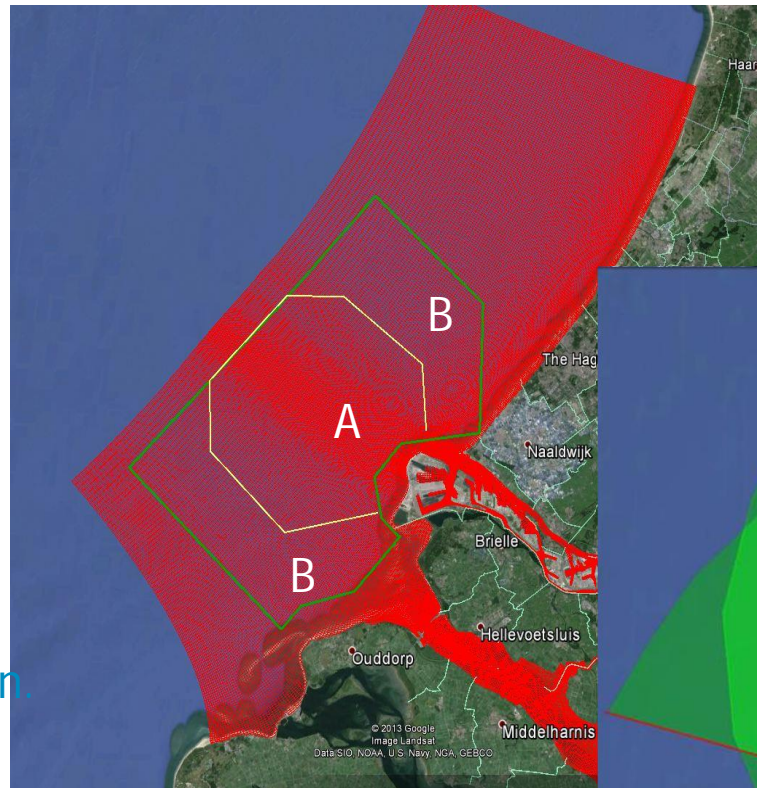
Data availability

Average 95%

up to Hs 5 m

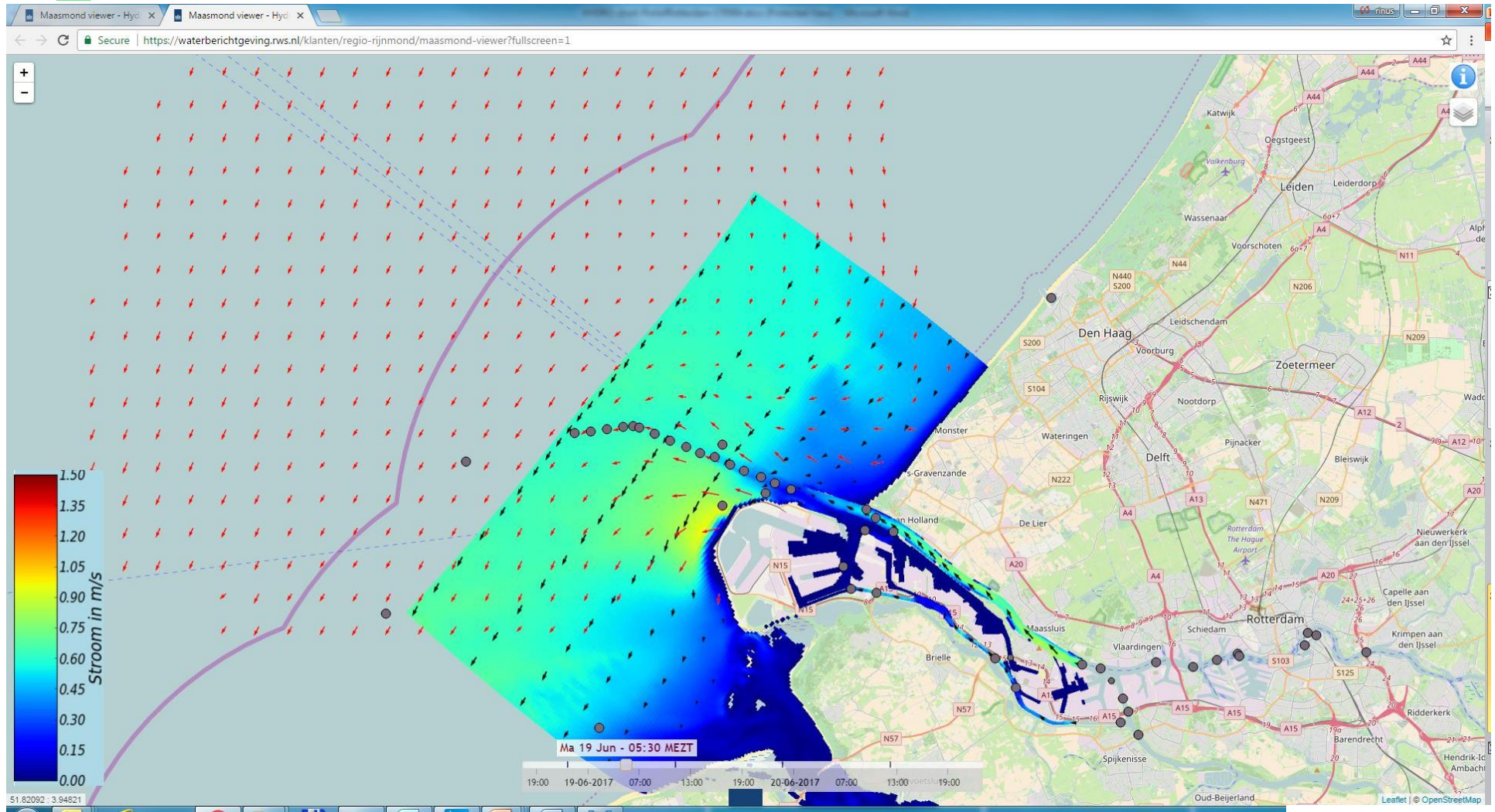
Time resolution

30 minutes





HF radar & 2D model

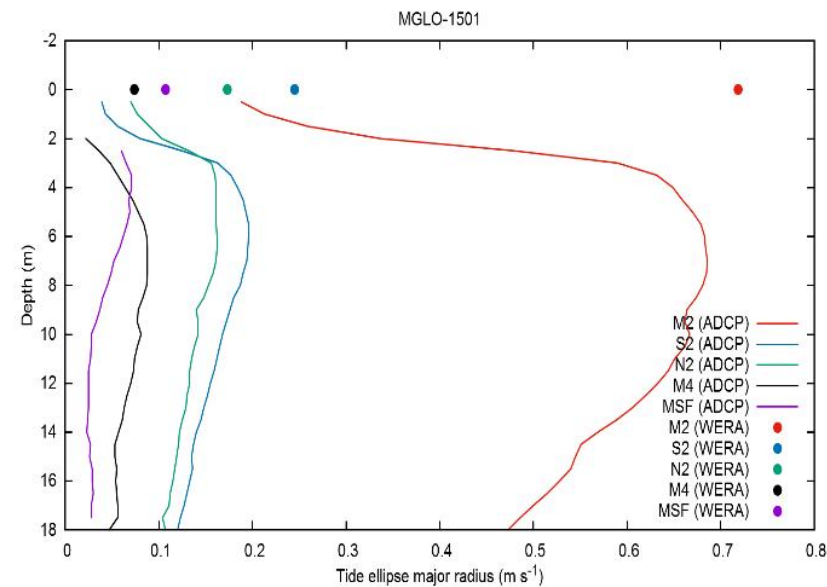


How to validate?

How to validate?



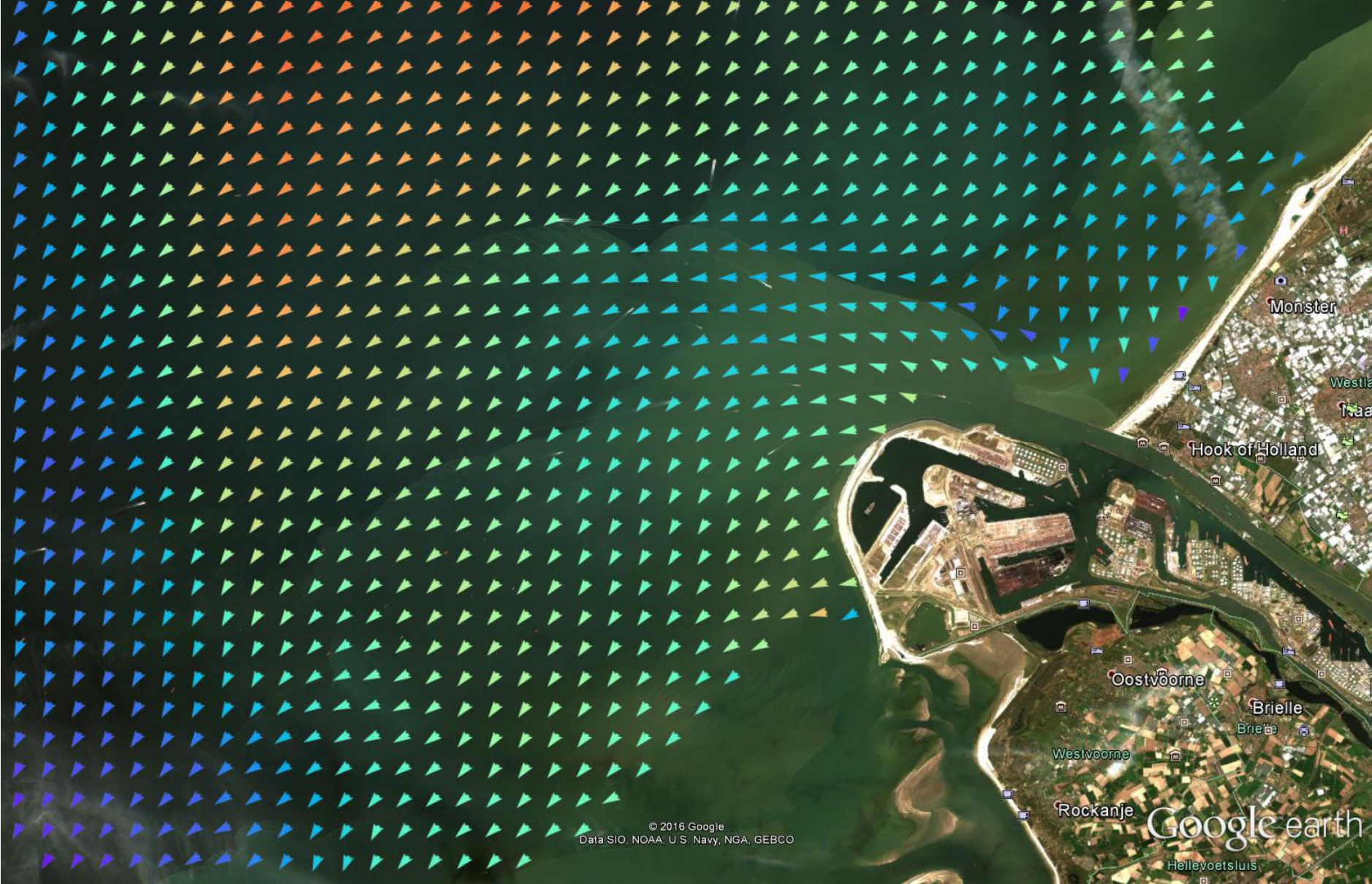
- Surface floats → shipping lane
- Fixed ADCP data → no surface measurement
- Ship based ADCP data → no surface measurement
-



Tidal components in currents:
Herron et al. 2016

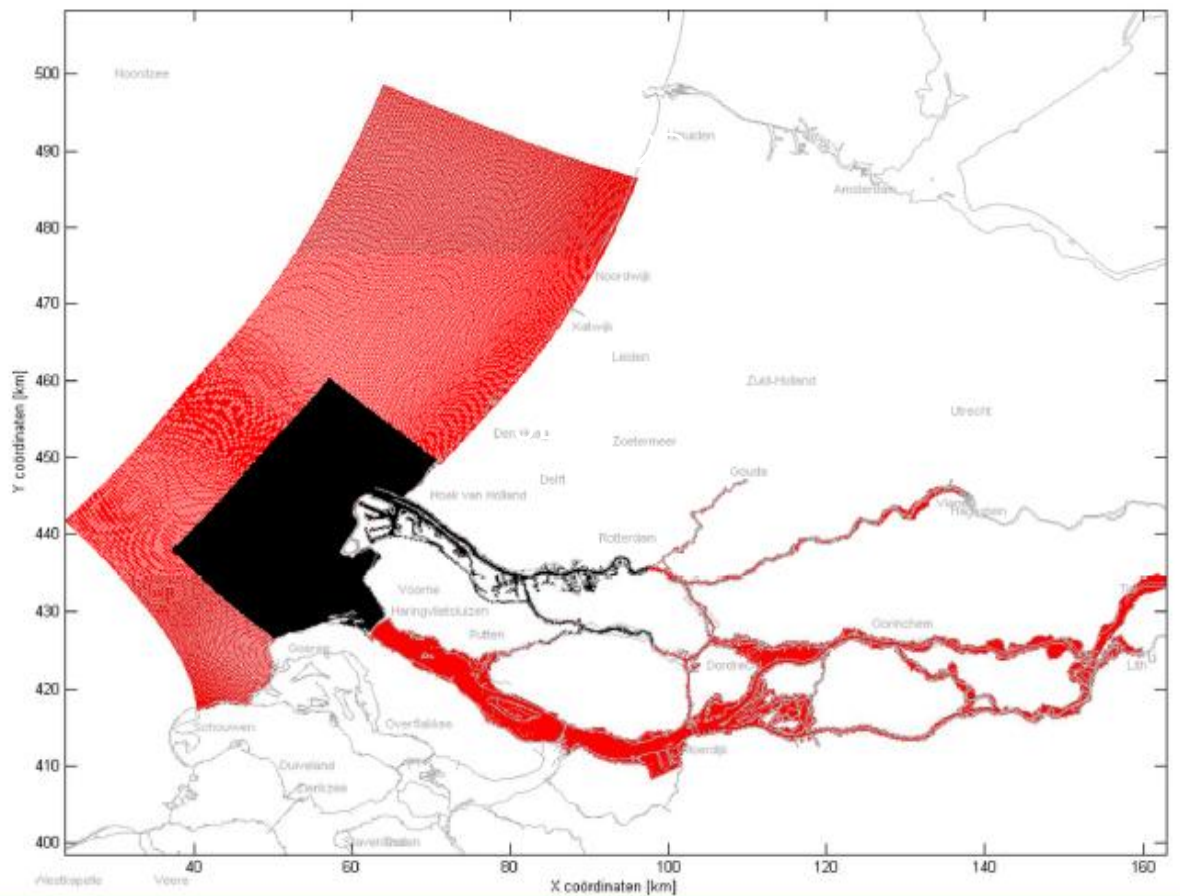


Satellite images



Short term model solution

1. Operational Flow model Port Rotterdam (nested 3D)
2. New D-Flow FM based on existing grids



Present status and planning



•2014

- HF radar specs (Deltares)
- Two temporary ADCP buoys installed

•2015

- HF radars operational mid 2015

Future?

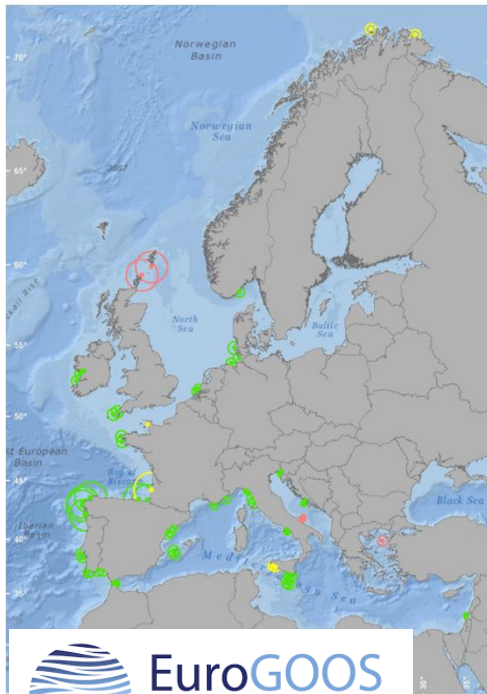
- First 3D model operational (short term solution)
- Data assimilation trials
- Full data assimilation of HF radar in model
- High end 3D model



HF radar work JERICO next



Harmonization & knowledge transfer



High Frequency radar task team

Documents

- New network systems: status of HF-radar systems and cabled coastal observatories.
- Best Practice for new network systems: HF-radar /cabled coastal observatories.
- Improved Radar DA technology for biochemical transport analysis
- Recommendation Report 1 for HFR data implementation in European infrastructures
- Recommendation Report 2 on improved common procedures for HFR QC analysis

Digging hole #1, Aug 18



Hole #1, Aug 18, immediately after dig. Timex image

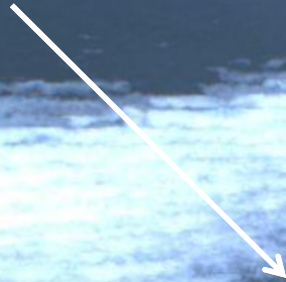
Cool megaripple features



Removed sand

Hole #1, Aug 18, day after dig. Brightest image

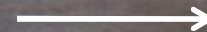
Hole?



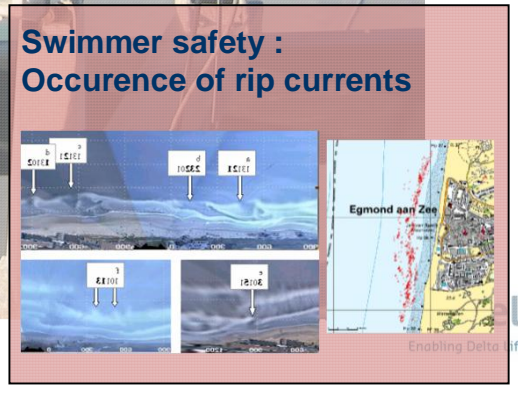
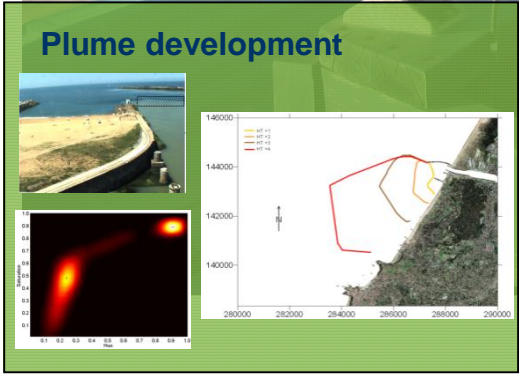
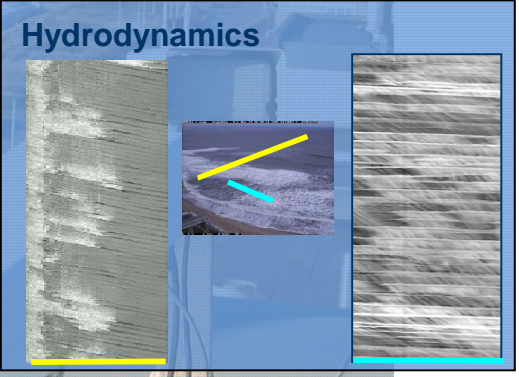
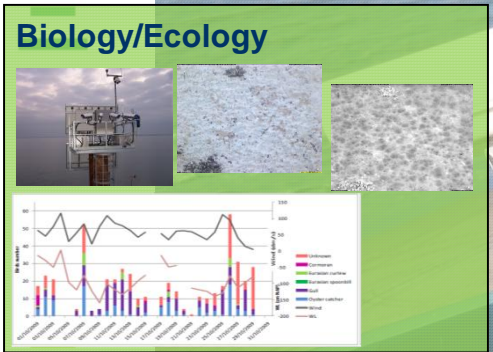
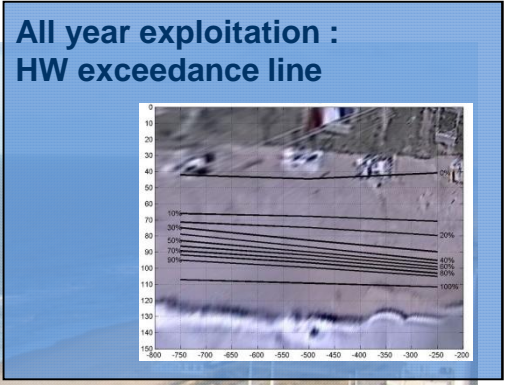
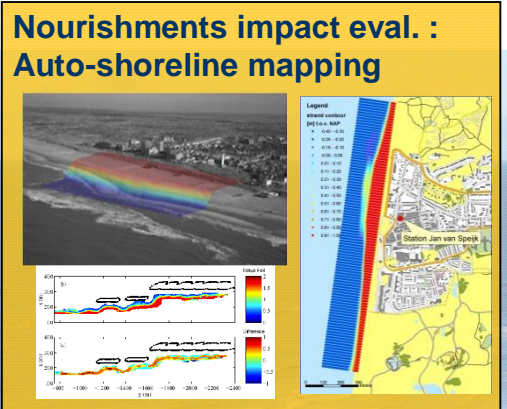
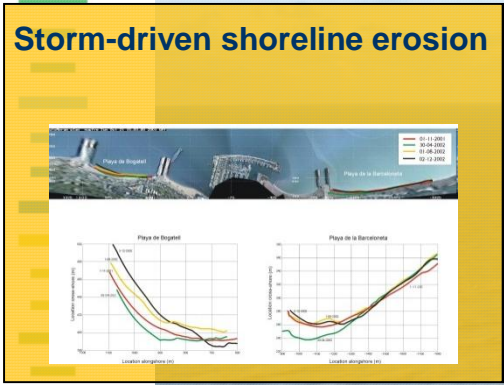
Highest swash



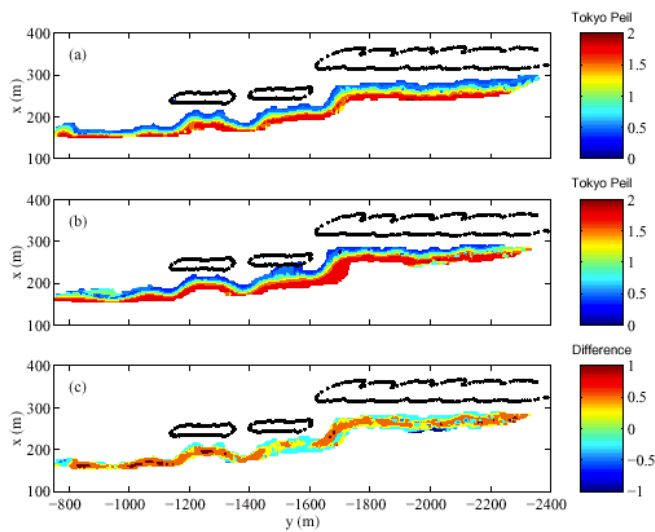
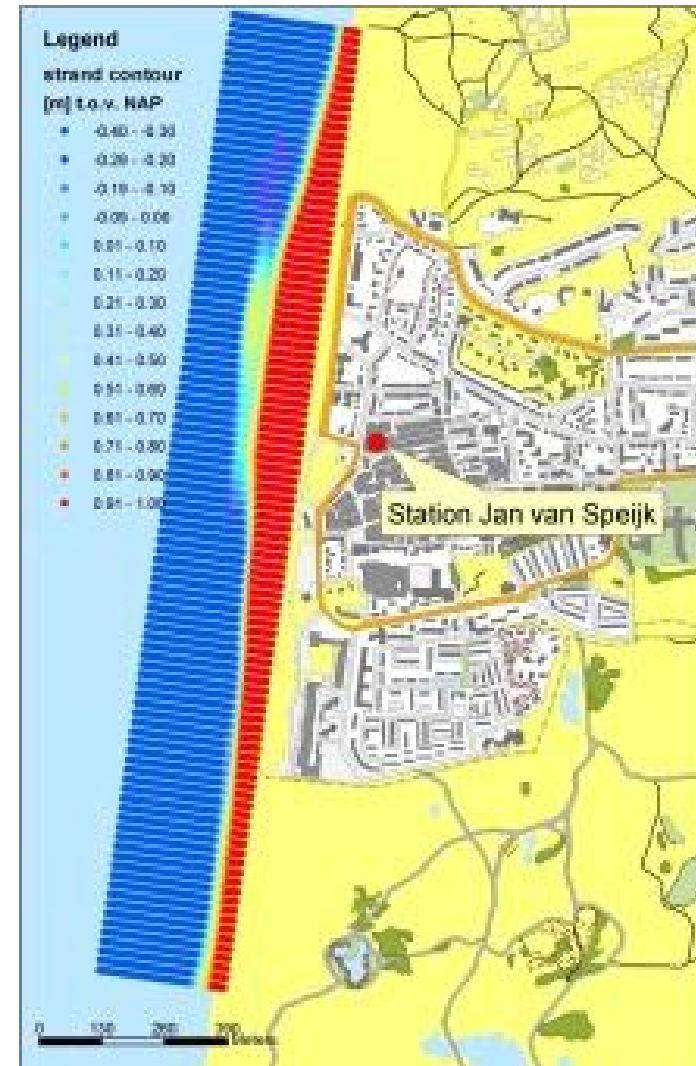
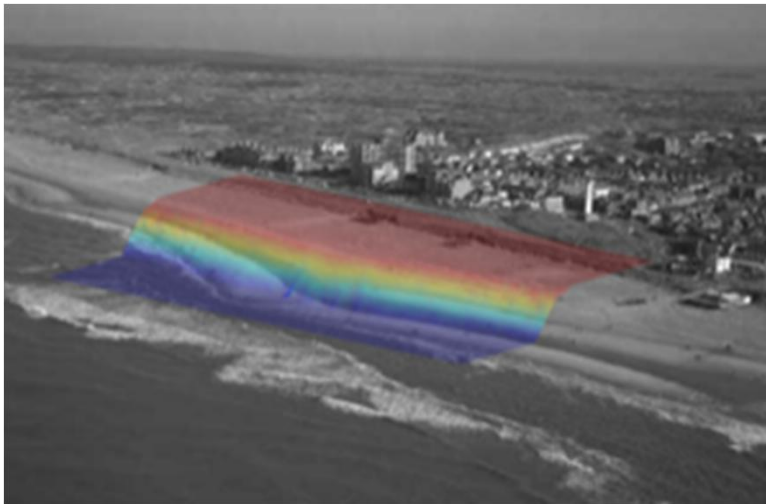
Walking surfer
(1/2 second captures)



Argus Coastal video monitoring applications



Shoreline development

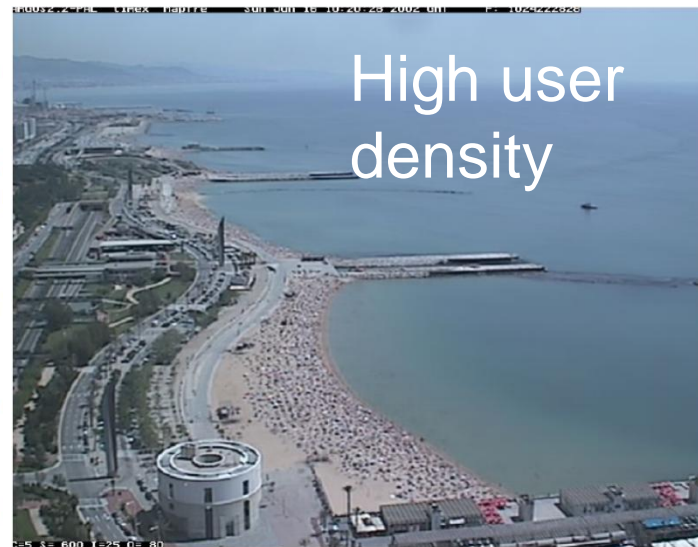


Recreation: beach use

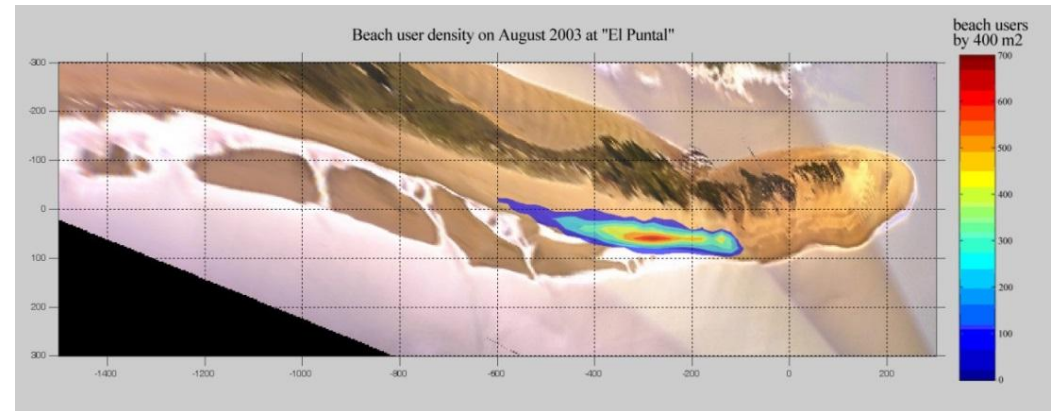


Low user density

Barcelona
Dr. Jorge Guillen

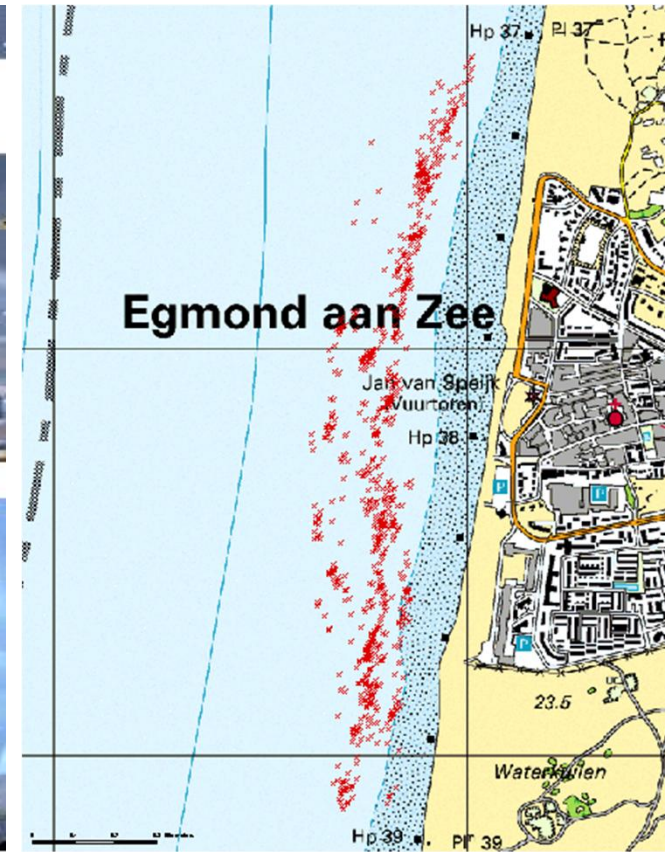
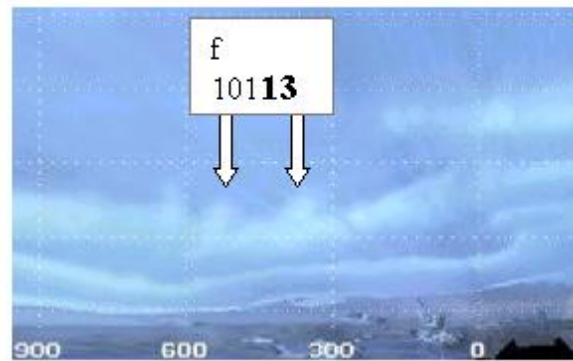
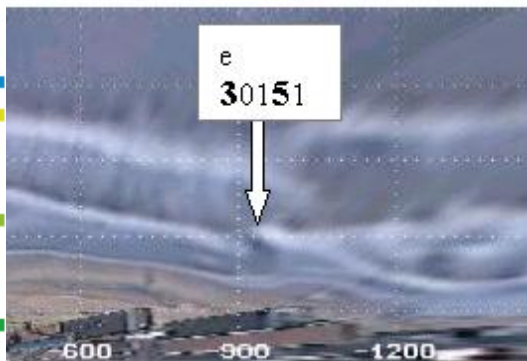
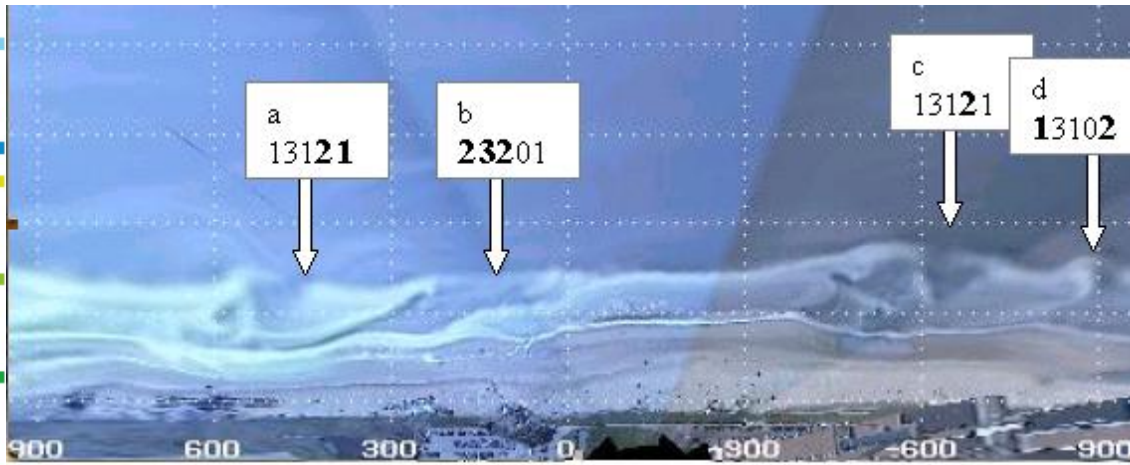


High user density



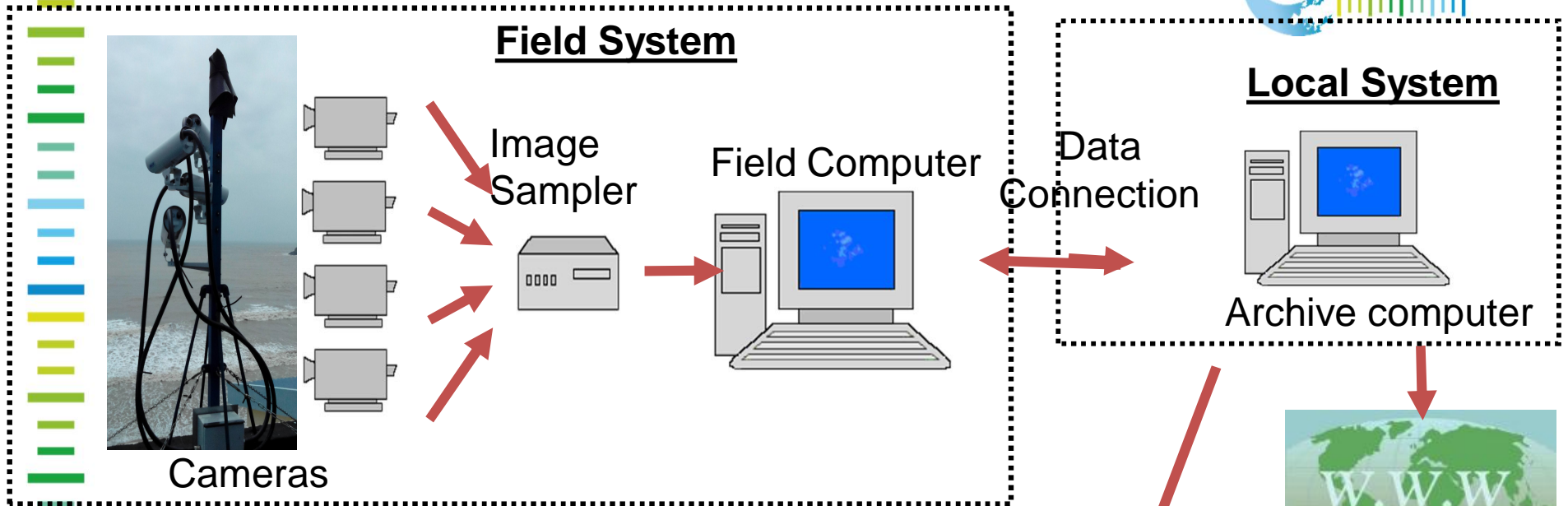
Santander
Raul Medina and Andres Osario

Recreation: Swimmer safety - Rip currents



Rip detection & classification

Rip occurrence Egmond,
May 1999 – June 2001



products ←

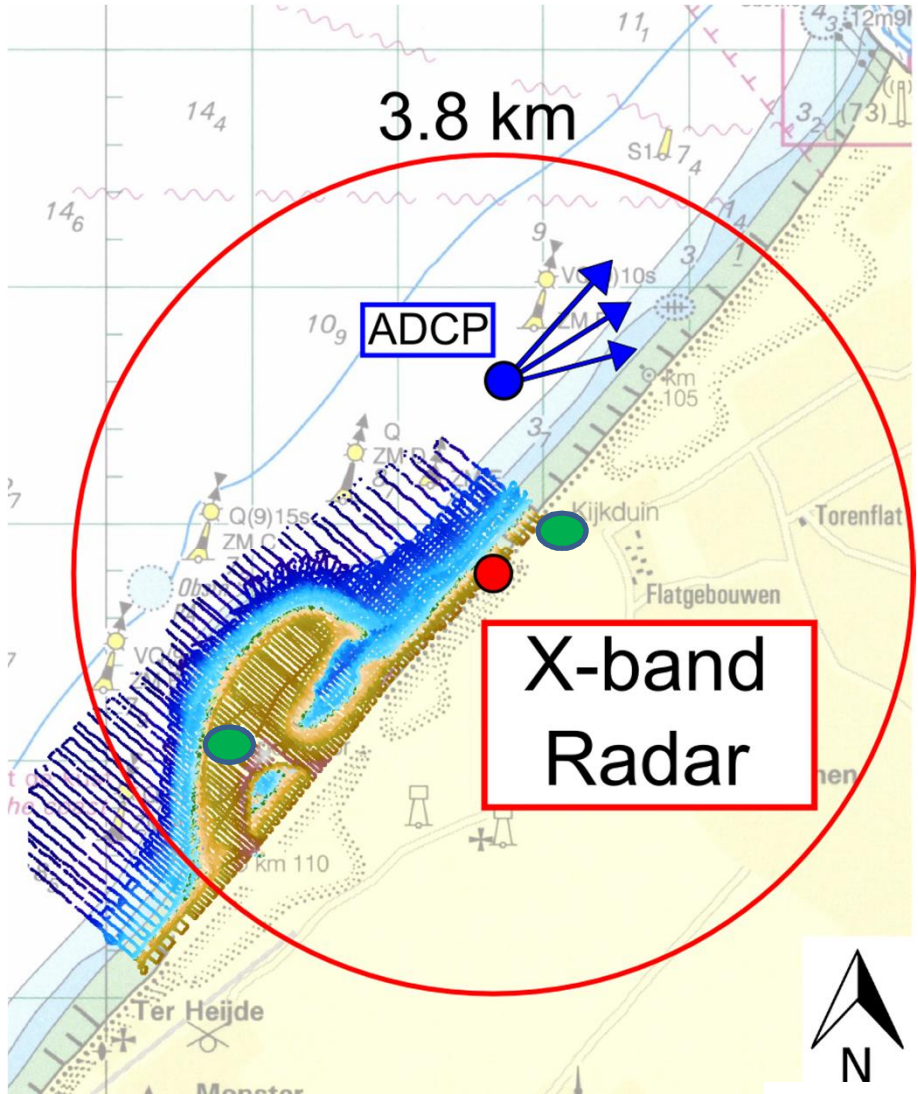


Pros: High-resolution, automated, low-cost, quick estimates

*Cons: Exact numbers take effort,
Complex due to multiple cameras*

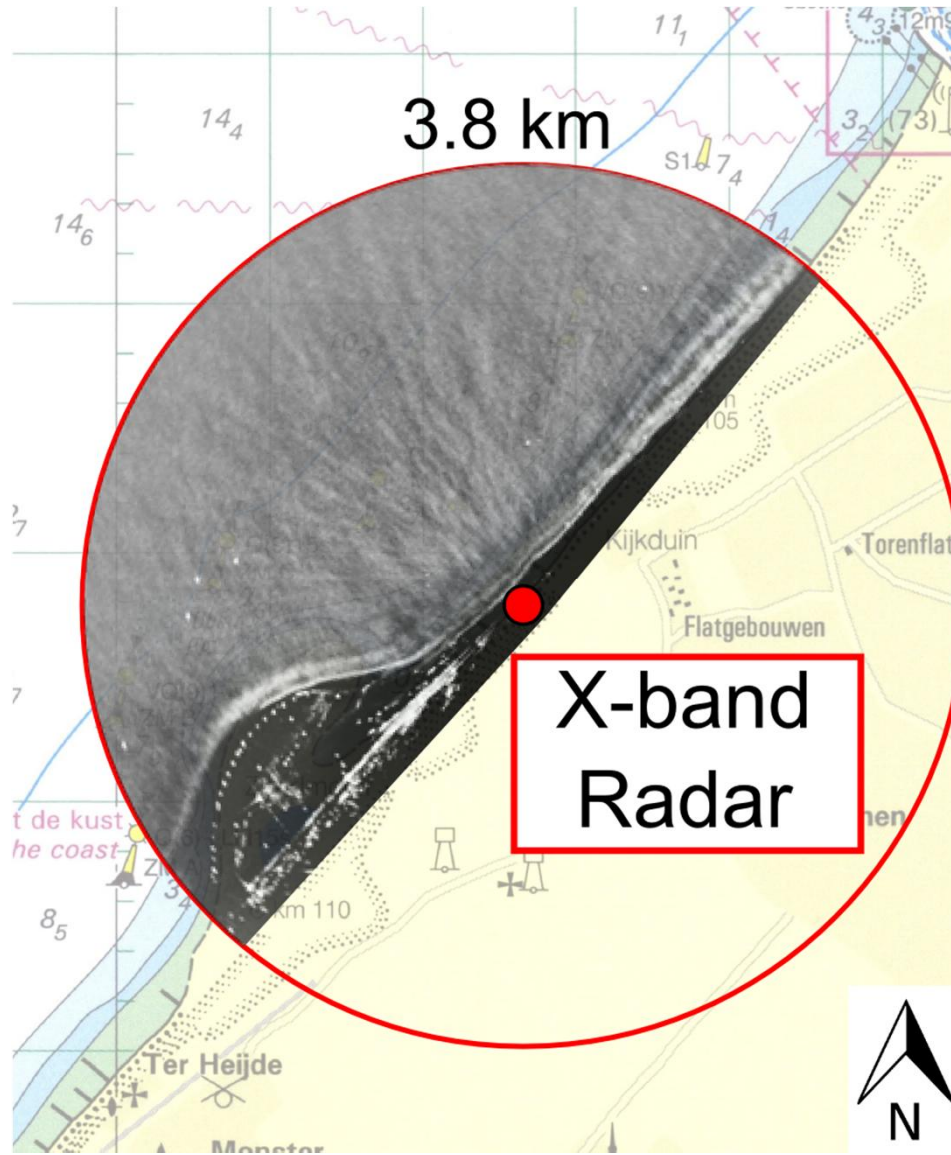


Monitoring Sand Motor

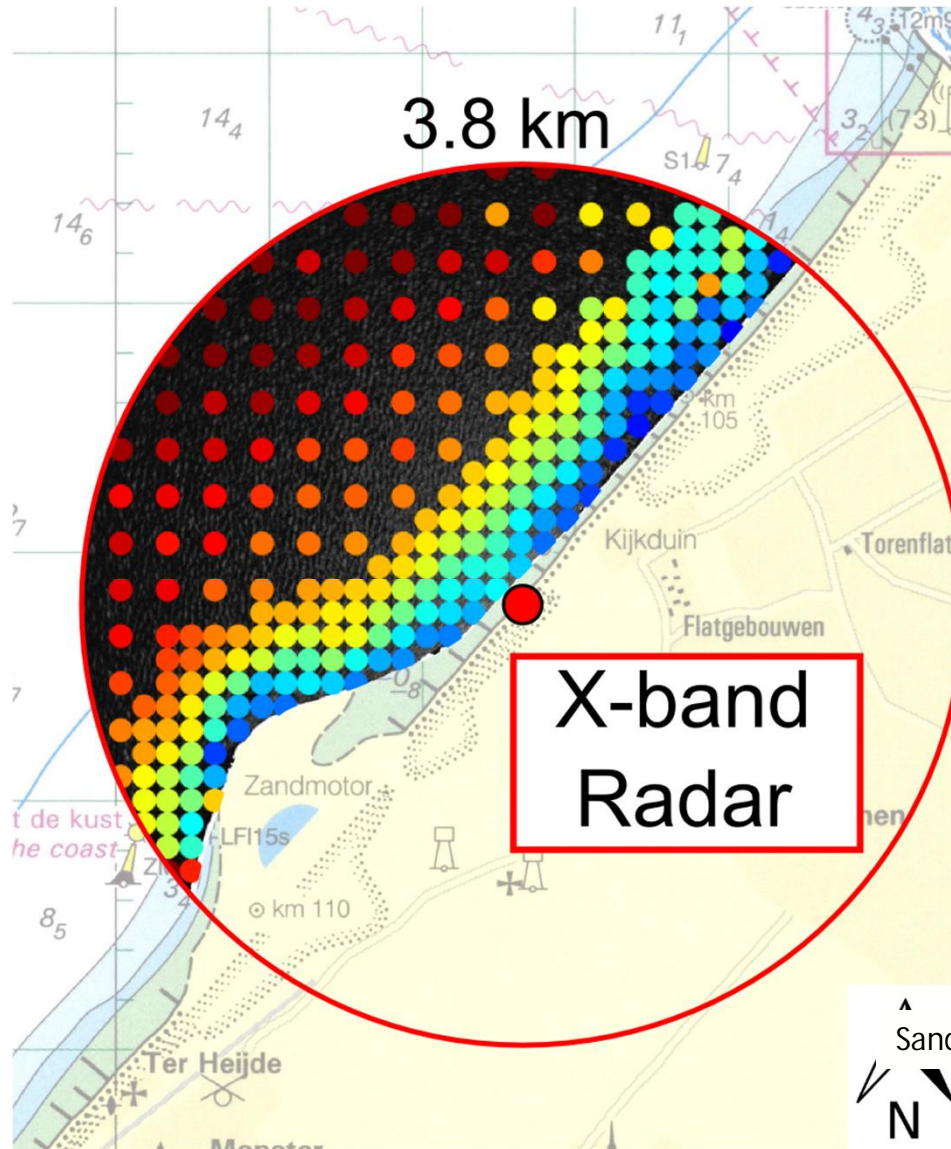




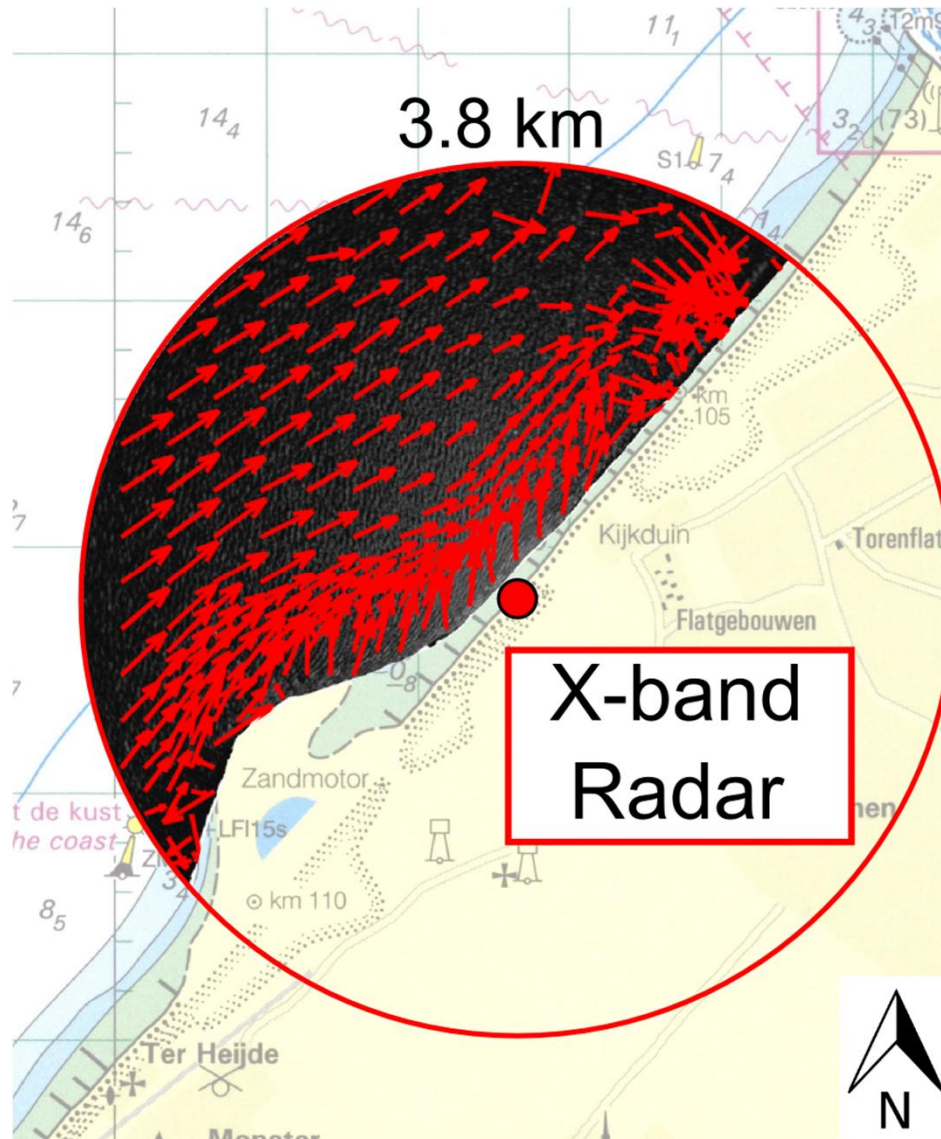
X-band raw data



X-band radar → Bathymetry



X-band radar → currents



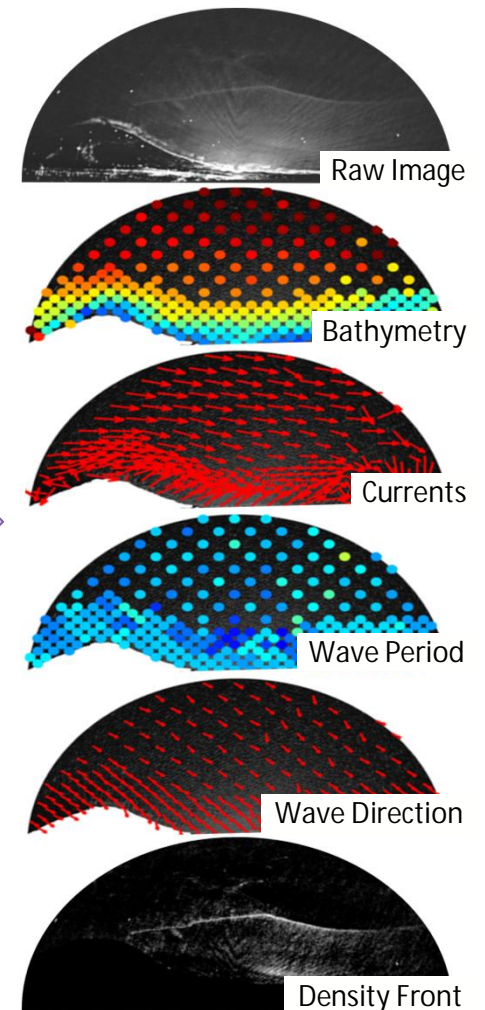
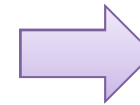
Raw data!

Sand Motor, Hydrodynamics Estimate

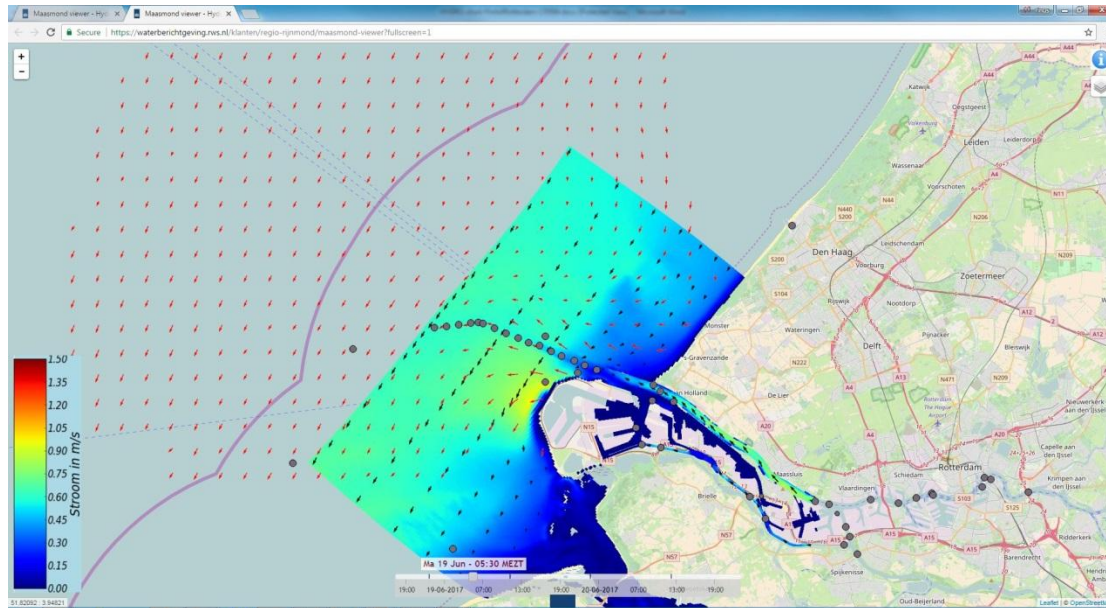
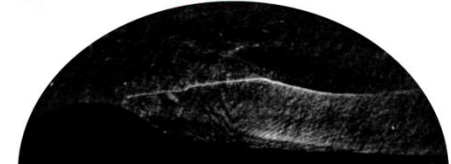
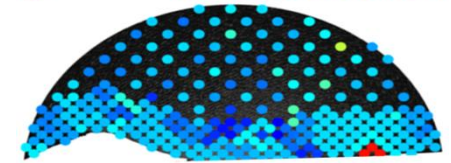
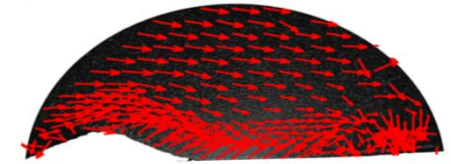
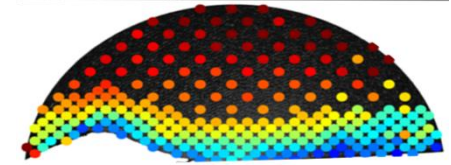
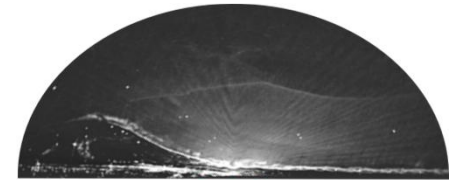
Application and potential users



- Existing hardware can be used to extract high resolution bathymetry and hydrodynamics
- Requires radar software for depth inversion
- Potential end users include:
 - Port authorities – dredging management, metocean limits, entrance channel navigability
 - Coastal engineers – implement in difficult coastal environments opposed to *in situ* measurements, use to validate numerical models
 - Researchers – improve the capabilities of depth inversion algorithms and quantify their uncertainty



Challenge: Combing RS data





Thank You



This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 654410.