

New sensors and techniques for in situ measurements at fixed points: image analysis and pH-pCO2 sensors (WP10.1 & 10.2)

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Coastal ecosystems are highly variable



the monitoring of all living and dead 'particles' requires integrated (all trophic levels) and rapid methods



Imaging systems, GREAT PERSPECTIVES

Provide indicators of ecosystem status (abundance, biomass, taxa, size spectra) from lab measurements and **in situ instruments** (provide high frequency data)

These indicators can be used to develop mathematical models for systems where size is important:

-zooplankton size spectra to get information on physiological rates (Platt & Denman 1978, ... Baird et al., 2004, 2010, Zhou 2006, Maury et al.,2007)

-vertical distribution of appendicularian and effect on vertical fluxes (Lombard et al., 2009)

-appendicularians in recent PFT models (Berline et al., 2010)

- vertical distribution of particle fluxes (Stemmann et al., 2004)

NOW and in the future: Pelagic ecosystem « end to end » monitoring



1: Flowcytometer











Task 10.1 Development of new tools and strategies for the monitoring of key biological compartments and processes.

Develop a sampling and an analytical protocol for the end to end pelagic ecosystem monitoring based on sample collection

•Use image analysis for the semi-automatic recognition of different plankton groups that could be used as indicators (bottles and net samples): FlowCam (for microplankton) and the Zooscan (for meso and macrozooplankton).

 Currently each instrument works with it's suite of softwares (Zooprocess/Plankton Identifier for Zooscan and ZooImage for Flowcam) while operational deployment requires an integrated and compatible methodologies.

Today, software is still an early version and does not include any features for automatic recognition.

OPERATION PILOTE POINT B: started in 2011



Nets and bottles for organisms 5 to 2000 μ m at VLFR (Point B site) during spring bloom and potentially in the Arcachon Lagoon

Sampling started and full analysis will be completed in spring 2012

OPERATION PILOTE POINT B: start in spring 2012



Image data base from FLOWCAM and ZOOSCAN exists and is used for image developing image analysis software

Develop an integrated suite of software for image analysis, automatic recognition, predictions validation and images and results management for both instruments

OPERATION PILOTE POINT B: started in 2011



Merging data from the different imaging systems works but requires adaptation for the software (in progress, should be finished early 2013)

Existing pH sensor: example of pH sensor developed by ULPGC (Melchor González Dávila mgonzalez@dqui.ulpgc.es)



A pH sensor has both been developed and trialed at ESTOC site (EUROSITES)



 pH_{T} daily variability 8.10 4 measurements per day and with SMS 8.08 transmission (coastal buoy in 2009) 8.06 pH_{T} 8.04 8.02 рН_{Т,is} pH_{T,25} 8.00 19 Jul 24 Jul 29 Jul 13 Aug 3 Aug 8 Aug

SP100-SM Submarine pH Sensor Based on spectrophotometric methods to measure pH removing dye effect in each determination

Range 0-20m. Work for 24 months with a pH reading every hour. Extremely stable pH sensor: precision < 0.002 pH units, accuracy \pm 0.005 pH units



Sensor deployed in 2011 on ESTOC site, including pCO2 from Pro-Oceanus



New design for E1-WM3A (HCMR)







Days, after 1st Jan 2010

WP10.2: Integration of pCO2 and pH sensors on EOL coastal buoy in Villefranche/Mer (near Nice)

Present pH time series record in the Villefranche Bay (by using water sampling every 2 weeks) are not enough to understand the pH variability and the reason of such variability (EPOCA, MedSea)







EOL buoy: possibility to crossvalidate data (in situ sampling), to transmit data by GSM and to check biofouling issues (10 min from lab)





High-Frequency Dynamics of Ocean pH: A Multi-Ecosystem Comparison

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Since 2009, the Martz lab (SIO) has constructed 52 **SeaFET pH** sensors for 13 different collaborators (see <u>http://martzlab.ucsd.edu</u>) working in a broad range of settings (9,850 US \$)

Autonomous indicator-based sensors for measurement of seawater pH. pH range 7.5-8.5; Accuracy 0.002; precision <0.001. Accomodates up to 3 additional sensors such as PAR, O2 optodes, beam-c transmissometers, and chl-a fluorometers.

🔀 CO2Pro160611.jpg

Pro-Oceanus sensor:

pCO2 by IR detection featuring automatic zero point calibration. High sampling rate; pumped interface; low cost; long term stability

